

```

1  function varargout = IIRS_RECOGNITION(varargin)
2  % IIRS_RECOGNITION m-file for IIRS
3
4  % Edit the above text to modify the function
5
6  % Default initialization code - DO NOT MODIFY
7  gui_Singleton = 1;
8  gui_State = struct('gui_Name',       mfilename, ...
9                    'gui_Singleton',  1, ...
10                   'gui_OpeningFcn', @IIRS_RECOGNITION_OpeningFcn, ...
11                   'gui_OutputFcn',  @IIRS_RECOGNITION_OutputFcn, ...
12                   'gui_LayoutFcn',   [] , ...
13                   'gui_Callback',    []);
14
15  % If nargin is not equal to numout, then return all
16  % outputs as a cell array.
17
18  if nargin <= numout
19      return(gui_State(varargin{:}));
20  end
21
22  % If nargin is not equal to numout, then return all
23  % outputs as a cell array.
24
25  if nargin <= numout
26      return(gui_State(varargin{:}));
27  end
28
29  % --- Executes just before IIRS_RECOGNITION is called from the command
30  % line.
31  function IIRS_RECOGNITION_OpeningFcn(hObject, eventdata, handles, varargin)
32  % This function has no output args, see OutputFcn
33  % hObject handle to figure
34  % eventdata reserved - to be defined in a future version of MATLAB
35  % handles structure with handles and user data (see GUIDATA)
36  % varargin command line arguments to IIRS_RECOGNITION (see VARARGIN)
37
38  % Choose default command line output for IIRS_RECOGNITION
39  handles.output = hObject;
40
41  % Create handles structure
42  guidata(hObject, handles);
43
44  % --- Executes just before IIRS_RECOGNITION is called from the command
45  % line.
46  function IIRS_RECOGNITION_OutputFcn(hObject, eventdata, handles)
47  % Get the current handles
48  handles = guidata(hObject);
49
50  % Return the outputs as a cell array
51  varargout{1:nargout} = handles.output;
52
53  % --- Executes just before IIRS_RECOGNITION is called from the command
54  % line.
55  function IIRS_RECOGNITION_DestroyFcn(hObject, eventdata, handles)
56  % Delete all the objects and reset the state
57  % hObject handle to figure
58  % eventdata reserved - to be defined in a future version of MATLAB
59  % handles structure with handles and user data (see GUIDATA)
60
61  % Delete the handles structure
62  guidata(hObject, []);
63
64  % End of IIRS_RECOGNITION.m

```



Iris Recognition System Source Code Using Java

**Václav Snášel,Ajit Abraham,Pavel
Krömer,Millie Pant,Azah Kamilah Muda**

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Intelligent Computing Systems Carlos Brito-Loeza, Anabel Martin-Gonzalez, Victor Castañeda-Zeman, Asad Safi, 2022-03-16 This book constitutes the proceedings of the 4th International Symposium on Intelligent Computing Systems ISICS 2022 held in Santiago Chile in March 2022 Due to the COVID 19 pandemic the conference was held online The 9 full papers along with 2 short papers presented in this volume were carefully reviewed and selected from 30 submissions They deal with the field of intelligent computing systems focusing on artificial intelligence computer vision and image processing

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